

# Efficient Combinatorial Schemes for Decoupling and Simulating Hamiltonians

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# Simulation of Hamiltonians

- let  $\mathcal{H} := \mathbb{C}^d$  be a closed quantum system with Hamiltonian  $H$
- we want to effectively change  $H$  to the desired Hamiltonian  $\tilde{H}$
- a simulation scheme adds a time-dependent **control Hamiltonian**  $H_c(t)$
- $H_c(t)$  is chosen such that the resulting dynamics is described by the effective Hamiltonian  $H_{\text{eff}}$  with

$$H_{\text{eff}} = \tilde{H}$$

# Simulation Tasks

- annihilation / maximal decoupling / time suspension

$$H \mapsto \tilde{H} = \mathbf{0}$$

- time-inversion / spin echo / Loschmidt echo

$$H \mapsto \tilde{H} = -H$$

- general simulation

$$H \mapsto \tilde{H}$$

# Simulation with Bang-Bang Controls

- the natural time evolution can be interspersed with **unitary bang-bang control operations**  $V_j$  drawn from some finite set  $\mathcal{C}$

$$V_N \exp(-iH\tau_N) \cdots V_2 \exp(-iH\tau_2) V_1 \exp(-iH\tau_1)$$

- the control scheme is cyclic:  $V_N V_{N-1} \cdots V_1 = \mathbf{1}$
- the corresponding **control propagators** are  $U_1 := \mathbf{1}$  and  $U_j := V_{j-1} \cdots V_1$  for  $j = 1, \dots, N - 1$
- the resulting dynamics can be expressed as

$$U_N^\dagger \exp(-iH\tau_N) U_N \cdots U_2^\dagger \exp(-iH\tau_2) U_2 U_1^\dagger \exp(-iH\tau_1) U_1$$

# Pictorial Representation

b.b. operations

$V_1$

$V_2$

$V_{N-1}$

$V_N$

|

$\tau_1$

|

$\tau_2$

|

$\dots$

|

$\tau_N$

|

propagators

$U_1$

$U_2$

$U_3$

$U_N$

$U_1$

# Effective Hamiltonian

- define the cycle length  $T_c := \sum_{j=1}^N \tau_j$
- define the time points  $t_M := MT_c$  for  $M \in \mathbb{N}$
- the stroboscopic dynamics  $U(t_M)$

$$U(t_M) := \left( U_N^\dagger \exp(-iH\tau_N) U_N \cdots U_1^\dagger \exp(-iH\tau_1) U_1 \right)^M$$

can be expressed as

$$U(t_M) = \exp(-i\bar{H}t_M)$$

for a **time-independent** effective Hamiltonian  $\bar{H}$

# Effective Hamiltonian

- Magnus expansion  $\bar{H} = \bar{H}^{(0)} + \bar{H}^{(1)} + \bar{H}^{(2)} + \dots$

$$\bar{H}^{(0)} = \frac{1}{T_c} \sum_{j=1}^N \tau_j U_j^\dagger H U_j$$

$$\bar{H}^{(1)} = \frac{-i}{2T_c} \sum_{1 \leq j < k \leq N} \tau_j \tau_k [U_j^\dagger H U_j, U_k^\dagger H U_k]$$

- $\|\bar{H}^{(m)}\| / \|\bar{H}^{(0)}\|$  are of order  $T_c^m$  for all  $m$
- $\Rightarrow$  truncation yields more and more accurate approximation as the fast control limit  $T_c \rightarrow 0$  is approached

# Approximation

- we focus on **first-order simulation**

$$\bar{H}^{(0)} = \frac{1}{T_c} \sum_{j=1}^N \tau_j U_j^\dagger H U_j$$

- by symmetrizing the control cycle

$$U_j = U_{N-j} \quad \text{and} \quad \tau_j = \tau_{N-j}$$

the terms  $\bar{H}^{(m)}$  can be made zero for all odd  $m$

- $\Rightarrow$  the simulation error is only  $O(T_c^2)$



# Summary: Bang-Bang Simulation

- let  $\mathcal{C}$  be the set of available bang-bang controls
- assume that the desired Hamiltonian  $\tilde{H}$  can be expressed as

$$\tilde{H} = \sum_{j=1}^N \tau_j U_j^\dagger H U_j$$

with  $V_j = U_j U_{j-1}^\dagger \in \mathcal{C}$

- then we can simulate  $\exp(-i\tilde{H})$  with  $N$  control operations, cycle time  $T_c = \sum_j \tau_j$ , and error  $O(T_c^2)$

# Simulation with Bounded-Strength Controls

- the assumption of bang-bang control is highly unrealistic
- more realistically, assume that the control Hamiltonian satisfies the properties
  - $\|H_c(t)\| \leq B$
  - $H_c(t)$  is a smooth function
- can we still simulate Hamiltonians?  
can we say something about time, number of control operations, and accuracy of the simulation?

# Control Propagator

- a simulation scheme is most conveniently constructed by directly looking at the propagator

$$U_c(t) = \mathcal{T} \exp \left\{ -i \int_0^t H_c(\tau) d\tau \right\}$$

- the control scheme is still cyclic

$$U_c(t + T_c) = U_c(t)$$

for some cycle time  $T_c$  and all  $t$

# Effective Hamiltonian

- the stroboscopic dynamics  $U(t_M)$  with  $t_M = MT_c$  and  $M \in \mathbb{N}$  can be described by

$$U(t_M) = \exp(-i\bar{H}t_M)$$

for a **time-independent** effective Hamiltonian  $\bar{H}$

- Magnus expansion  $\bar{H} = \bar{H}^{(0)} + \bar{H}^{(1)} + \bar{H}^{(2)} + \dots$

$$\bar{H}^{(0)} = \frac{1}{T_c} \int_0^{T_c} U_c^\dagger(\tau) H U_c(\tau) d\tau$$

# Group-Theoretic Tools

- let  $G$  be a finite group and  $\mathcal{U} := \{U_g : g \in G\}$  a set of unitary matrices acting on  $\mathcal{H} := \mathbb{C}^d$  s.t.

the map  $g \mapsto U_g$  is compatible with multiplication in  $G$  up to phase factors:  $U_{gh} = \omega(g, h)U_gU_h$  with  $|\omega(g, h)| = 1$

- assume that  $G$  and  $\mathcal{U}$  are chosen s.t.

$$\frac{1}{|G|} \sum_{g \in G} U_g^\dagger X U_g = \frac{\text{Trace}(X)}{d} \mathbf{1}_d$$

for any operator  $X$  acting on  $\mathcal{H}$

- let  $S \subset G$  be a generating set for  $G$ : every element in  $G$  can be written as a product of elements in  $S$

# Example

•  $\mathcal{H} := \mathbb{C}^2$ ,  $G := Z_2 \times Z_2$ , and  $\mathcal{U} := \{\mathbf{1}, X, Y, Z\}$

$$(0, 0) \mapsto \mathbf{1}$$

$$(1, 0) \mapsto X$$

$$(0, 1) \mapsto Z$$

$$(1, 1) \mapsto Y$$

• generalizes to  $\mathcal{H} := \mathbb{C}^d$

# Elementary Control Hamiltonians

assume we can physically implement the generators  $s \in S$ :

we can obtain  $U_s$  as control propagators by switching on some suitably chosen bounded-strength time-dependent control Hamiltonians  $h_s(t)$  over  $[0, \Delta]$

$$U_s = u_s(\Delta)$$

where

$$u_s(\delta) = \mathcal{T} \left\{ \exp\left(-i \int_0^\delta h_s(t) dt\right) \right\}$$

for  $\delta \in [0, \Delta]$

# Group / Graph - Theoretic Tools

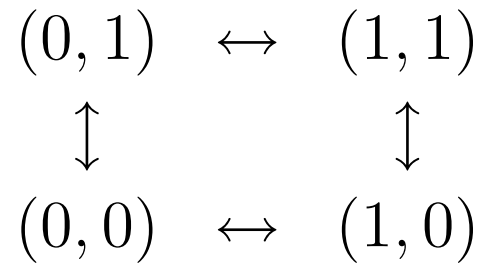
- let  $\Gamma := \Gamma(G, S)$  be the **Cayley graph** of  $G$  with respect to the generating set  $S$ 
  - the vertices are group elements  $g \in G$
  - the directed edges are labeled by generators  $s \in S$
  - there is an edge from  $g$  to  $h$  iff

$$gs = h$$

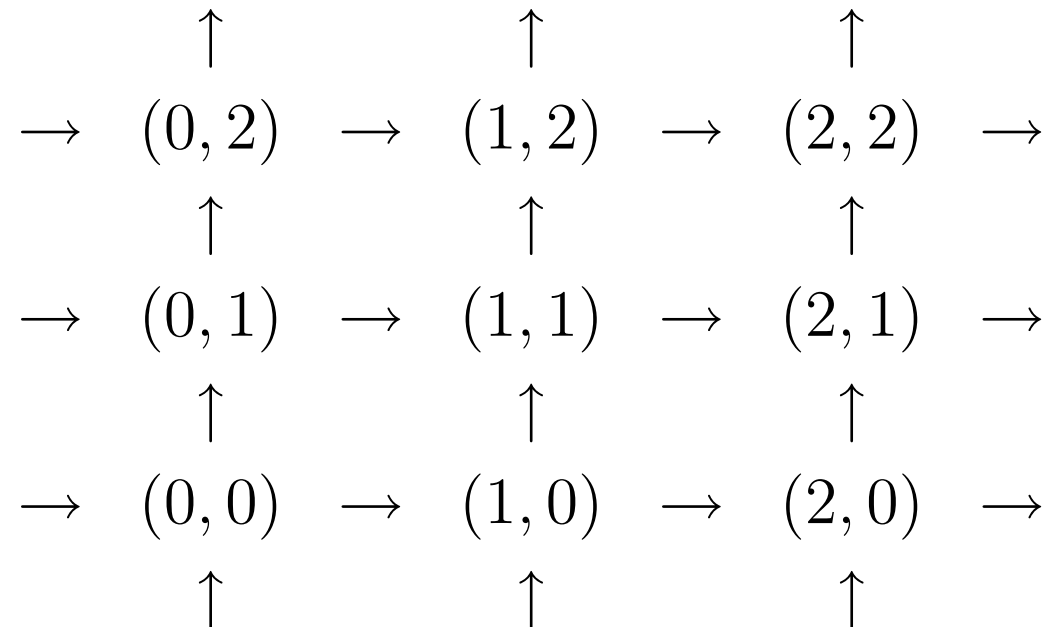


# Examples of Cayley Graphs

•  $G := Z_2 \times Z_2$  and  $S = \{(0, 1), (1, 0)\}$



•  $G := Z_3 \times Z_3$  and  $S = \{(0, 1), (1, 0)\}$



# Group / Graph - Theoretic Tools

- a sequence  $(g_1, s_1; g_2, s_2; \dots; g_N, s_N)$  of group elements and generators is called an **Euler cycle** iff
  - $g_{j+1} = g_j s_j$  for  $j = 1, \dots, N - 1$
  - $g_N s_N = g_1$
  - each pair  $(g, s)$  occurs exactly once in the sequence for all  $g \in G$  and  $s \in S$

w.l.o.g we choose  $g_1$  to be the identity element  $e$

# Properties of Euler Cycles

the Euler cycle

- visits every vertex  $g \in G$  exactly  $|S|$  times
- each vertex  $g$  is left via each of the  $s$ -labeled edges ( $s \in S$ ) exactly once

$$\Rightarrow N = |S||G|$$

# Example

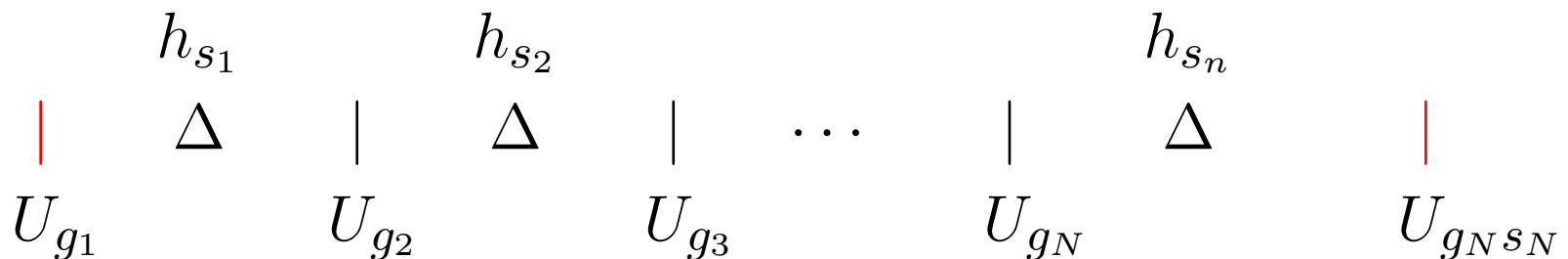
•  $G := Z_2 \times Z_2$  and  $S = \{(0, 1), (1, 0)\}$

$$\begin{array}{ccc} (0, 1) & \leftrightarrow & (1, 1) \\ \downarrow & & \downarrow \\ (0, 0) & \leftrightarrow & (1, 0) \end{array}$$

Euler cycle: start at  $(0, 0)$ , go clockwise, and then go counter-clockwise

# Annihilation Based on Euler Cycles

- let  $(g_1, s_1; g_2, s_2; \dots; g_N, s_N)$  be an Euler cycle
- set the cycle length  $T_c := N\Delta$
- the control Hamiltonian  $H_c(t)$  is obtained by switching on the elementary control Hamiltonians according to the Euler cycle



# Analysis of Euler Annihilation Scheme

- to analyze the resulting dynamics it is very useful to define the map  $\Pi_G$

$$\Pi_G(X) = \frac{1}{|G|} \sum_{g \in G} U_g^\dagger X U_g$$

and the maps  $F_s$  for  $s \in S$

$$F_S(X) = \frac{1}{|S|} \sum_{s \in S} \int_0^\Delta \frac{1}{\Delta} u_s(t)^\dagger X u_s(t) dt$$

- Why?

INTUITION: recall that each pair  $(g, s)$  occurs exactly once in the Euler cycle

# Analysis of Euler Annihilation Scheme

- the effective Hamiltonian can be expressed as

$$\begin{aligned}\bar{H} &= \frac{1}{T_c} \int_{t=0}^{T_c} U_c(t)^\dagger H U_c(t) dt \\ &= \Pi_G[F_S(H)] \\ &= \mathbf{0}\end{aligned}$$

# Euler Simulation Scheme

- assume the desired Hamiltonian can be written as

$$\tilde{H} = \sum_{g \in G} \tau_g U_g^\dagger H U_g$$

- set  $T_c := N\Delta + \sum_g \tau_g$
- implement the Euler annihilation cycle, but wait for  $\tau_{g_j}/|S|$  after each  $g_j$

$$\begin{array}{ccccccc}
 & h_{s_{j-1}} & & \mathbf{0} & & h_{s_j} & & \mathbf{0} \\
 & \Delta & & \frac{\tau_{g_j}}{|S|} & & \Delta & & \frac{\tau_{g_{j+1}}}{|S|} \\
 U_{g_{j-1}} & | & U_{g_j} & | & U_{g_j} & | & U_{g_{j+1}} & | & U_{g_{j+1}}
 \end{array}$$



# Analysis of Euler Simulation Scheme

- the effective Hamiltonian can be expressed as

$$\begin{aligned}\bar{H} &= \frac{1}{T_c} \int_{t=0}^{T_c} U_c(t)^\dagger H U_c(t) dt \\ &= \Pi_G[F_S(H)] + \frac{1}{T_c} \sum_{g \in G} \tau_g U_g^\dagger H U_g \\ &= \frac{1}{N\Delta + \sum_g \tau_g} \tilde{H}\end{aligned}$$

the term  $N\Delta$  does not occur when b.b. controls are available

# Combinatorial Bang-Bang Annihilation

- assume that the quantum system  $\mathcal{H} := (\mathbb{C}^2)^{\otimes n}$  consists of  $n$  coupled qubits
- assume that the set of bang-bang control operations is  $\mathcal{C} := \{1, X, Y, Z\}^{\otimes n}$ , i.e., the qubits can be addressed individually
- $\Rightarrow$  the set of control propagators is  $\mathcal{U} := \{1, X, Y, Z\}^{\otimes n}$

# Inefficient Annihilation Scheme

- apply the control operations to the qubits in such that each unitary in  $\mathcal{U} := \{1, X, Y, Z\}^{\otimes n}$  is obtained exactly once as control propagator
- this defines an annihilation scheme since

$$\frac{1}{4^n} \sum_{U \in \mathcal{U}} U^\dagger X U = \frac{\text{Trace}(X)}{4^n} \mathbf{1}_{4^n}$$

for any operator acting on  $\mathcal{H} := (\mathbb{C}^2)^{\otimes n}$

- this scheme is highly inefficient since the number of control operations is  $N = 4^n$  and the cycle time  $T_c = 4^n \Delta$

bad: exponential scaling with the number of qubits  $n$

# 2-local Hamiltonian

- we take advantage of the fact that the system Hamiltonian is 2-local

$$H := \sum_{k < l} H_{kl}$$

where  $H_{kl}$  denotes couplings between qubits  $k$  and  $l$

# Orthogonal Arrays

- let  $\mathcal{A}$  be a finite set of cardinality  $s$  and  $n, N \in \mathbb{N}$
- an  $n \times N$  array  $A$  with entries from  $\mathcal{A}$  is an **orthogonal array** with
  - $s = |\mathcal{A}|$  levels
  - strength  $t$
  - index  $\lambda$

iff every  $t \times N$  sub-array of  $A$  contains each possible  $t$ -tuple of elements in  $\mathcal{A}$  precisely  $\lambda$  times as a column

# Example

- an orthogonal array with parameters  $N = 16$ ,  $n = 5$ ,  $s = 4$ , and  $t = 2$

$$\begin{pmatrix} 1 & 1 & 1 & 1 & X & X & X & X & Y & Y & Y & Y & Z & Z & Z & Z \\ 1 & X & Y & Z & Z & Y & X & 1 & 1 & X & Y & Z & Z & Y & X & 1 \\ 1 & Y & Z & X & 1 & Y & Z & X & Y & 1 & X & Z & Y & 1 & X & Z \\ 1 & Y & Z & X & Z & X & 1 & Y & Z & X & 1 & Y & 1 & Y & Z & X \\ 1 & X & Y & Z & X & 1 & Z & Y & Z & Y & X & 1 & Y & Z & 1 & X \end{pmatrix}$$

# Construction of OAs

Theorem: Construction of OAs from error-correcting codes

- let  $C$  be a linear  $[n, k, d]_q$  code over  $\mathbb{F}_q$
- let  $d^\perp$  be the minimum distance of the dual code  $C^\perp$
- arrange the code words of  $C$  into the columns of a matrix  $M \in \mathbb{F}_q^{n \times q^k}$   
 $\Rightarrow M$  is an  $OA(q^k, n, q, d^\perp - 1)$

# Annihilation Schemes based on OA

- apply the bang-bang control operations on the qubits such that the resulting control propagators follow the columns of the orthogonal array  $OA(n, N, 4, \lambda)$
- this defines an annihilation scheme for arbitrary (even unknown) 2-local Hamiltonians on  $n$  qubits with  $N$  control operations and cycle time  $T_c = N\Delta$
- it is efficient since  $N$  scales only linearly with  $n$



# Combinatorial Euler Annihilation

- assume that the available bounded-strength control Hamiltonians  $h_X(t)$  and  $h_Z(t)$  implement the unitary operations  $X$  and  $Z$  if they are switch on for time  $\Delta$
- assume that these control Hamiltonians can be realized on the qubits in  $\mathcal{H} = (\mathbb{C}^2)^{\otimes n}$  individually

# Euler Orthogonal Arrays

- we combined Euler annihilation with orthogonal arrays
- this yields annihilation schemes for arbitrary 2-local Hamiltonians on  $n$  qubits with  $N = O(n \log n)$  control operations and cycles time  $T_c = O(n \log N \Delta)$
- the cost is only increased by the factor  $\log n$  compared to the bang-bang setting

# Conclusion

- adjust these techniques to realistic scenarios
- extend to open system setting

$$H = H_S \otimes \mathbf{1}_E + \mathbf{1}_S \otimes H_E + \sum_a S_a \otimes B_a$$

- simulation of Hamiltonians while decoupling from the environment

$$H \mapsto \tilde{H}_S \otimes \mathbf{1}_E + \mathbf{1}_S \otimes H_E$$

- simulation of open system Hamiltonian

$$H \mapsto \tilde{H}_S \otimes \mathbf{1}_E + \mathbf{1}_S \otimes H_E + \sum_a \tilde{S}_a \otimes B_a$$